





Virtual DGPS Based on SBAS Signal

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Background



> The low elevation angles to the GEO satellites at high latitudes (ranging from 4-22 degrees from Finland to the EGNOS GEO satellites), make it difficult to access the SBAS services for land applications.



EGNOS GEO satellites are not visible in city canyons even in central Europes.



It takes very long to initiate the SBAS positioning process when the availability of the SBAS SIS is low.



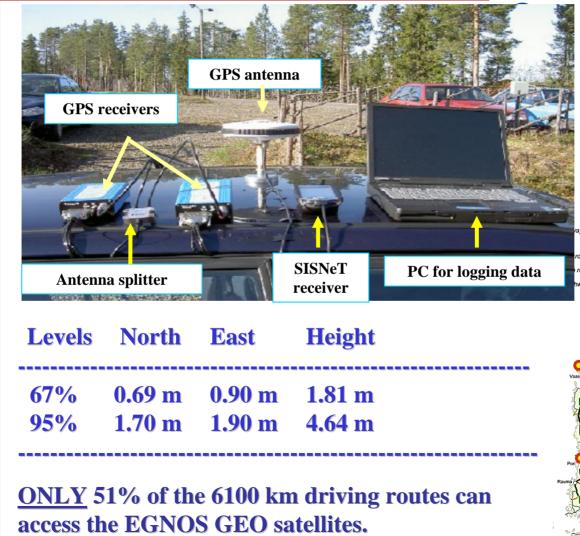
Access to the SBAS service via the old DGPS receivers





EGNOS Positioning Accuracy and SIS Availability in Finland







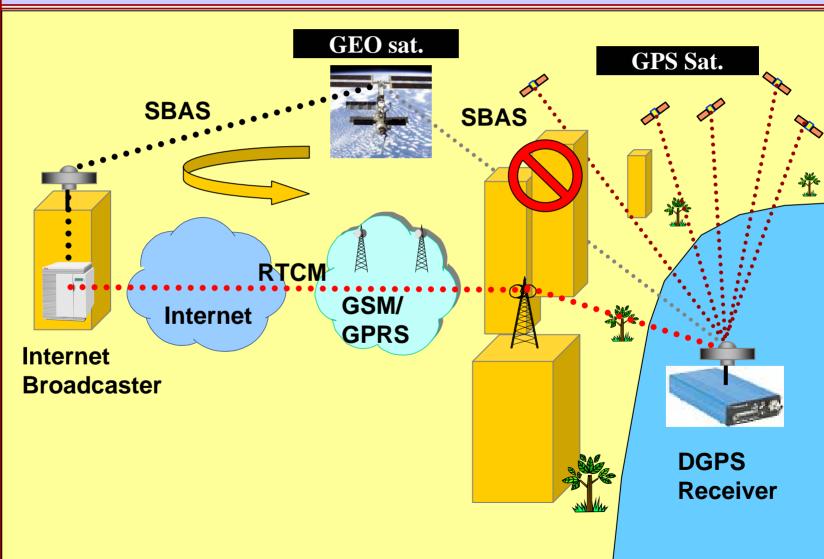


Virtual DGPS-Concept







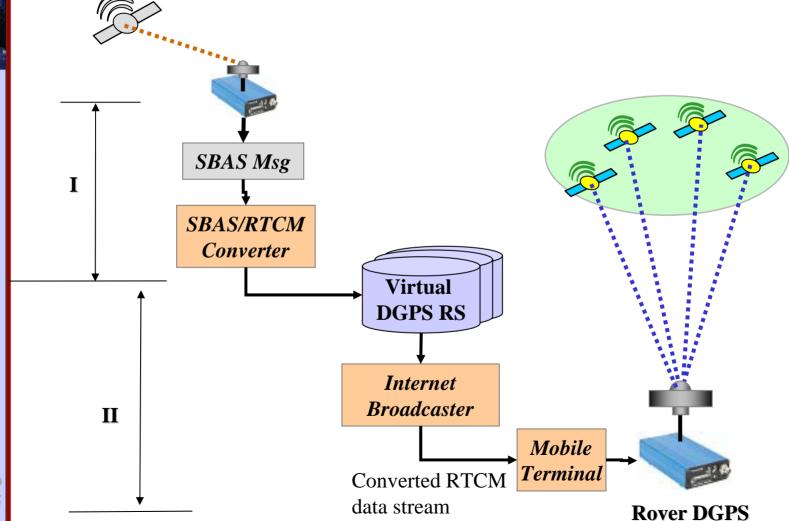






Virtual DGPS - Infrastructure





receiver

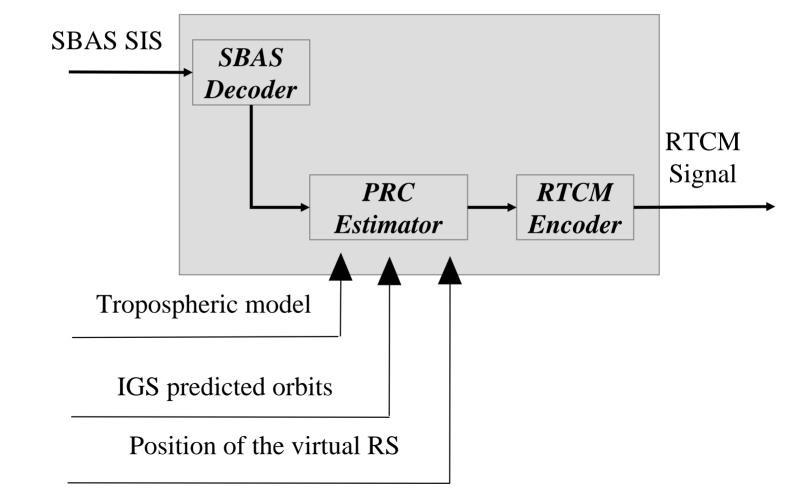






SBAS/RTCM Converter







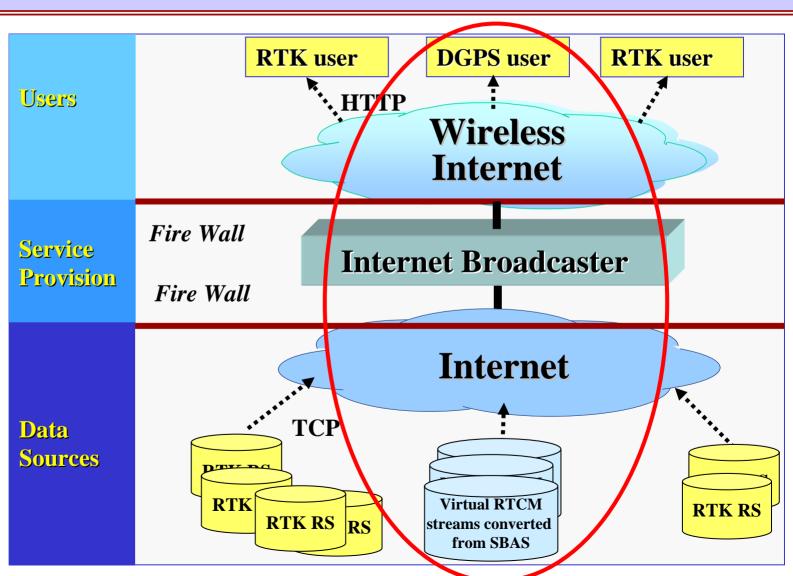


Internet Broadcaster – the Concept







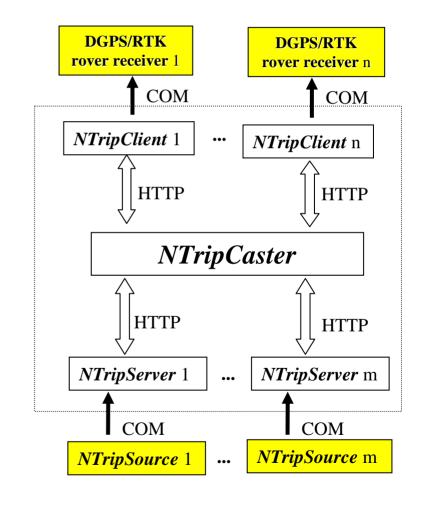




Internet Broadcaster The NTRIP Concept



- It is based on the Internet radio technology (IceCast).
- It consists of three components: NtripSource, NtripCaster and NtripClient
- It supports the multiple-tomultiple solutions for network-based RTK solutions.
- It can be used for the transmission of other data streams e.g IGS predicted orbits.
- The NTRIP protocal is developed by the German Fedreal Agency of Cartography and Geodesy



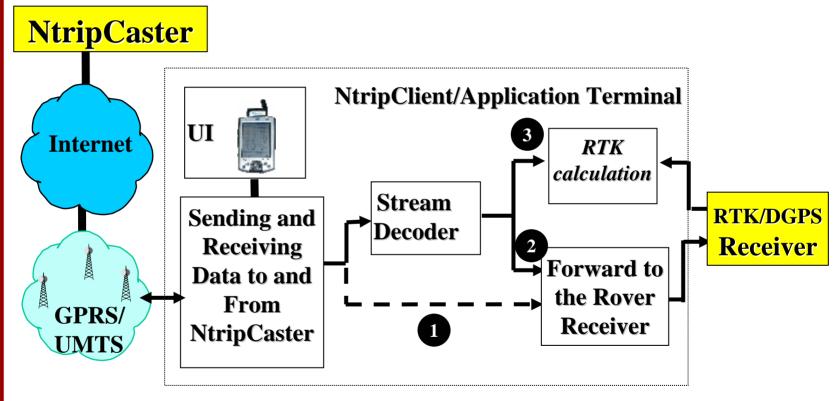






Development of the NtripClient **Three Development Options**











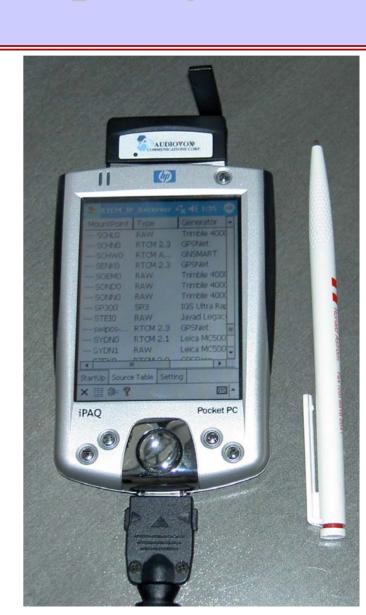
The NtripClient Developed by FGI



RTCM_IP	Recei	ver	3	8:46p	(ok)	
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— GORLO	RAW		Javao	d Lega		
— GOTH0	RAW		Triml	rimble 400		
$-HAMBO_1$	RTCM	2.1	GPSN	Vet V2		
-HANNO	RTCM	2.1	GPSN	Vet V2	.	
— HELJO	RAW		Javad	Javad Legac		
HELSO 2	RTCA		Thale	es DG-:	1	
—HELS1	RTCM	3.0	Thale	es DG-	1	
- SP300 (4)	SP3		IGS (Jitra Ra	3	
-HOERO	RO RAW		Javad Legac			
$-$ HOLTO $_{3}$	-HOLTO(3) RAW			Javad Legac		
-HUEGO	RAW		Javad Legac			
— ILMEO	RAW		Trimble 400 📦			
4				•	_	
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Screen shot of the NtripClient showing different kinds of active data streams including 1)RTCM data streams, 2) RTCA data streams, 3)raw data and 4)a SP3 IGS ultra-rapid orbits.

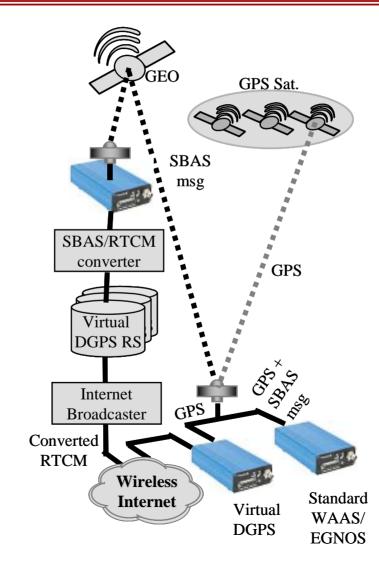






Test Configuration



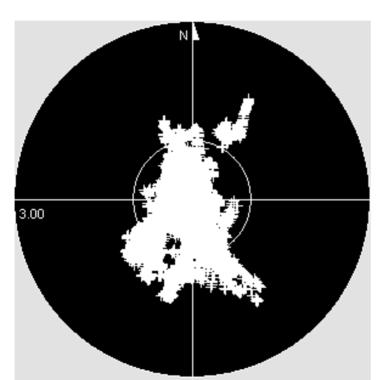


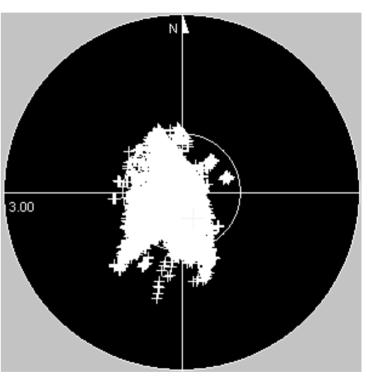




SBAS vs. Virtual DGPS







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SBAS

Virtual DGPS

Inner ring = 1m

Outer ring = 3m



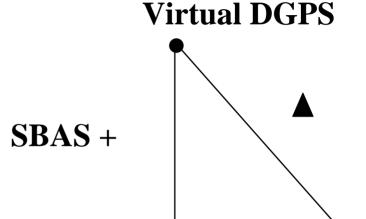
Ionospheric Vertical Delay Interpolation Improvement



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SBAS Algorithm





$$v_p = \sum_{i=1}^n w_i \cdot v_i$$

with
$$w_i = \frac{\int_{s_i^2}^{1/s_i^2}}{\sum_{1/s_i}^{n}}$$
 $n = 1\Lambda 3$

$$n = 1\Lambda 3$$



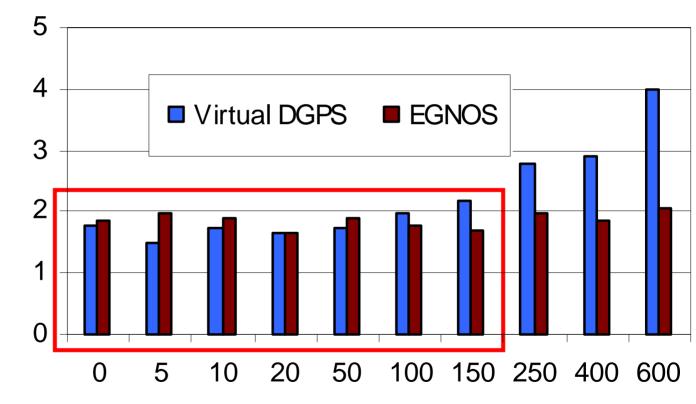




Accuracy Degradation at Different Distances



Horizonal errors at 95% (m)





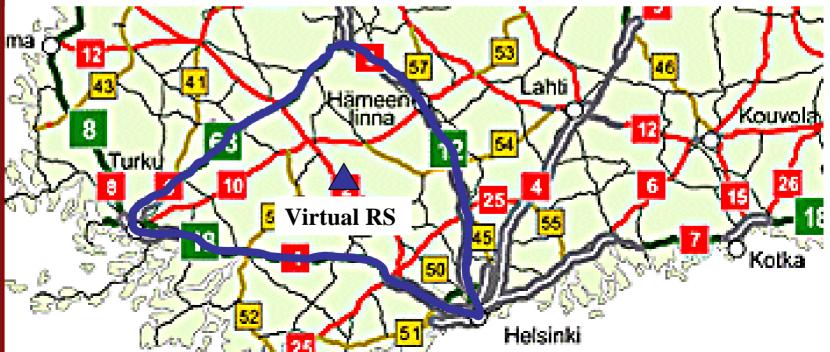
Distances to the virtual reference station (km)



Availability Test



A preliminary driving test of 400 kilometers in southern Finland showed that the availability of the virtual DGPS solutions was 98.6% along the driving route.







Benifits of Virtual DGPS



- > Provide similar positioning accuracy as DGPS.
- ➤ Overcome the limitation of low elevation angles to the GEO satellites and increase the SBAS positioning availability at high latitudes and city canyons.
- ➤ Made it possible to access the SBAS service via a legacy DGPS receiver.
- ➤ No initiation process is needed. The end users can access to the SBAS service immediately when they made a connection to the Internet broadcaster.







Benifits of Virtual DGPS cont'd



- ➤ Virtual DGPS reference stations can be created anytime anywhere within the SBAS service area.
- ➤ No investments and maintenance work for a DGPS network are needed as it is a virtual solution.





Conclusions



- ➤ The virtual DGPS solution provides a positioning accuracy of 1-2 meters, which is similar to that of the standard WAAS/EGNOS solution.
- ➤ The accuracy is not degraded as long as the rover receiver is within the radius of 150 kilometers from the virtual reference station.
- ➤ A preliminary driving test of 400 kilometers in southern Finland showed that the availability of the virtual DGPS solutions was 98.6% along the driving route.





Future Works



- FGI is now updating the data communication system of the permanent GPS network, it is expected that the real-time data will be available in 2005.
- The concept can be extended by integrating the local permanent GPS network to EGNOS system to improve the positioning accuracy.



